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Regularized Newton Method with **Global** $O(1/k^2)$ Convergence

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One World Optimization Seminar

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Regularized Newton Method with Global $O(1/k^2)$ Convergence

Konstantin Mishchenko

We present a Newton-type method that converges fast from any initialization and for arbitrary convex objectives with Lipschitz Hessians. We achieve this by merging the ideas of cubic regularization with a certain adaptive Levenberg--Marquardt penalty. In particular, we show that the iterates given by

$x^{k+1} = x^k - \left(\nabla^2 f(x^k) + \sqrt{H \|\nabla f(x^k)\|} \mathbf{I} \right)^{-1} \nabla f(x^k)$, where $H > 0$ is a constant, converge globally with a $\mathcal{O}(\frac{1}{k^2})$ rate. Our method is the first variant of Newton's method that has both cheap iterations and provably fast global convergence. Moreover, we prove that locally our method converges superlinearly when the objective is strongly convex. To boost the method's performance, we present a line search procedure that does not need hyperparameters and is provably efficient.

Comments: 19 pages, 1 figure

Subjects: **Optimization and Control (math.OC)**; Machine Learning (cs.LG)

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(or [arXiv:2112.02089v1](https://arxiv.org/abs/2112.02089v1) [math.OC] for this version)

Submission history

From: Konstantin Mishchenko [[view email](#)]

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Talk structure

- 1. Problem**
- 2. Historical remarks**
- 3. Key idea**
- 4. Theory overview**
- 5. Experiments**
- 6. Conclusion**

Problem

$$\min_{x \in \mathbb{R}^d} f(x)$$



**Convex and has
Lipschitz Hessian**

Problem

$$\min_{x \in \mathbb{R}^d} f(x)$$

$$\nabla^2 f(x) \succcurlyeq 0$$

Problem

$$\min_{x \in \mathbb{R}^d} f(x)$$

$$\nabla^2 f(x) \succcurlyeq 0$$

$$\|\nabla^2 f(x) - \nabla^2 f(y)\| \leq 2H \|x - y\|$$

 Some constant

Newton's method

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

Newton's method

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

In practice, solve $\mathbf{A}\delta = b$

with $\mathbf{A} = \nabla^2 f(x^k)$, $b = -\nabla f(x^k)$

$$x^{k+1} = x^k + \delta$$

Newton's method

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

In practice, solve $\mathbf{A}\delta = b$

with $\mathbf{A} = \nabla^2 f(x^k)$, $b = -\nabla f(x^k)$

$$x^{k+1} = x^k + \delta$$

Linear systems are easy

Newton's method

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

Extremely fast locally

Newton's method

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

Extremely fast locally

Does not converge globally

Line search and trust-region

$$x^{k+1} = x^k - t_* (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

Line search and trust-region

$$x^{k+1} = x^k - t_* (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

$$t_* = \arg \min_{t \geq 0} f(x^k - t (\nabla^2 f(x^k))^{-1} \nabla f(x^k))$$

Line search and trust-region

$$x^{k+1} = x^k - t_* (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

$$t_* = \arg \min_{t \geq 0} f(x^k - t(\nabla^2 f(x^k))^{-1} \nabla f(x^k))$$

Full Length Paper | [Published: 24 May 2015](#)

Simple examples for the failure of Newton's method with line search for strictly convex minimization

[Florian Jarre](#) & [Philippe L. Toint](#) 

[Mathematical Programming](#) **158**, 23–34 (2016) | [Cite this article](#)

Talk structure

1. **Problem**
2. **Historical remarks**
3. **Key idea**
4. **Theory overview**
5. **Experiments**
6. **Conclusion**

Historical remarks

- **Ancient Greek, Babylonian and Arab mathematicians, solving equations by improving estimates**

HISTORICAL DEVELOPMENT OF THE NEWTON-RAPHSON METHOD*

TJALLING J. YPMA[†]

Abstract. This expository paper traces the development of the Newton-Raphson method for solving nonlinear algebraic equations through the extant notes, letters, and publications of Isaac Newton, Joseph Raphson, and Thomas Simpson. It is shown how Newton's formulation differed from the iterative process of Raphson, and that Simpson was the first to give a general formulation, in terms of fluxional calculus, applicable to nonpolynomial equations. Simpson's extension of the method to systems of equations is exhibited.

Historical remarks

- Ancient Greek, Babylonian and Arab mathematicians, solving equations by improving estimates
- Viète, 1600, solving polynomial equation $p(x)=0$
- Newton, 1669, improved method of Viète (polynomials)
- Raphson, 1690, simpler iterative approach (not just polynomials)
- Simpson, 1740, solving systems of 2 equations using derivatives

Early development

Historical remarks

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- Simpson, 1740, solving systems of 2 equations using derivatives
- Kantorovich, 1939, linear convergence rate for general $F(x)=0$
- Mysovskikh, 1949, modern proof with quadratic rate
- Davidon, 1959, DFP
- Broyden, Fletcher, Goldfarb, and Shanno, 1970, BFGS

Modern methods and proofs

Historical remarks

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- Viète, 1600, solving polynomial equation $p(x)=0$
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- Davidon, 1959, DFP
- Broyden, Fletcher, Goldfarb, and Shanno, 1970, BFGS
- Griewank, 1981, numerics for cubic Newton
- Nesterov & Polyak, 2006, theory for cubic Newton

Most relevant works: Cubic Newton

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Newton and cubic Newton methods

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

Newton and cubic Newton methods

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

$$\begin{aligned} f(x) &\approx f(x^k) + \langle \nabla f(x^k), x - x^k \rangle \\ &\quad + \frac{1}{2} \langle \nabla^2 f(x^k)(x - x^k), x - x^k \rangle \end{aligned}$$

2nd-order Taylor approximation

Newton and cubic Newton methods

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

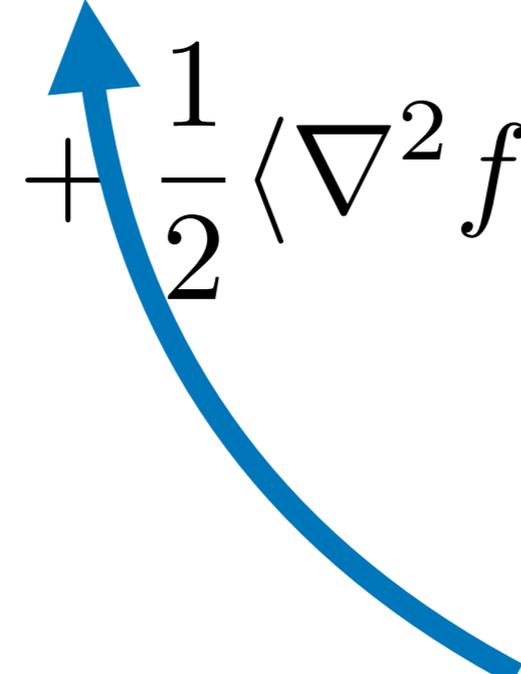
$$f(x) \approx f(x^k) + \langle \nabla f(x^k), x - x^k \rangle$$
$$+ \frac{1}{2} \langle \nabla^2 f(x^k)(x - x^k), x - x^k \rangle$$



Newton and cubic Newton methods

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  $\|x - x^k\| \approx 0$

Local by design

Newton and cubic Newton methods

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

$$\begin{aligned} f(x) &\leq f(x^k) + \langle \nabla f(x^k), x - x^k \rangle \\ &\quad + \frac{1}{2} \langle \nabla^2 f(x^k)(x - x^k), x - x^k \rangle \\ &\quad + \frac{H}{3} \|x - x^k\|^3 \end{aligned}$$

Global bound

Newton and cubic Newton methods

$$x^{k+1} = x^k - (\nabla^2 f(x^k))^{-1} \nabla f(x^k)$$

$$\begin{aligned} f(x) &\leq f(x^k) + \langle \nabla f(x^k), x - x^k \rangle \\ &\quad + \frac{1}{2} \langle \nabla^2 f(x^k)(x - x^k), x - x^k \rangle \\ &\quad + \frac{H}{3} \|x - x^k\|^3 \end{aligned}$$

Global bound

$$\|\nabla^2 f(x) - \nabla^2 f(y)\| \leq 2H \|x - y\|$$

Newton and cubic Newton methods

$$~~x^{k+1} = x^k + (\nabla^2 f(x^k))^{-1} \nabla f(x^k)~~$$

$$x^{k+1} = \arg \min_x \left\{ \langle \nabla f(x^k), x - x^k \rangle + \frac{1}{2} \langle \nabla^2 f(x^k)(x - x^k), x - x^k \rangle + \frac{H}{3} \|x - x^k\|^3 \right\}$$

Nesterov & Polyak, 2006

Griewank, 1981

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$$\nabla f(x^k) + \nabla^2 f(x^k)(x^{k+1} - x^k) + H \|x^{k+1} - x^k\| (x^{k+1} - x^k) = 0$$

Newton and cubic Newton methods

$$\del{x^{k+1} = x^k + (\nabla^2 f(x^k))^{-1} \nabla f(x^k)}$$

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Converges globally

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Converges globally

But no closed-form expression!

Newton and cubic Newton methods

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Lemma. It holds $H \|x^{k+1} - x^k\| \approx \sqrt{H \|\nabla f(x^{k+1})\|}$.

Newton and cubic Newton methods

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Idea. Maybe $H \|x^{k+1} - x^k\| \approx \sqrt{H \|\nabla f(x^k)\|}$?

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Almost!

Newton and cubic Newton methods

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Idea. Maybe $H \|x^{k+1} - x^k\| \approx \sqrt{H \|\nabla f(x^k)\|}$?

Almost! **We can prove one side**

$$H \|x^{k+1} - x^k\| \leq \sqrt{H \|\nabla f(x^k)\|}$$

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Proposed method

$$x^{k+1} = x^k - \left(\nabla^2 f(x^k) + \sqrt{H \|\nabla f(x^k)\| \mathbf{I}} \right)^{-1} \nabla f(x^k)$$

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$$\|\nabla^2 f(x) - \nabla^2 f(y)\| \leq 2H \|x - y\|$$

Global convergence

$$x^{k+1} = x^k - \left(\nabla^2 f(x^k) + \sqrt{H \|\nabla f(x^k)\| \mathbf{I}} \right)^{-1} \nabla f(x^k)$$

Theorem. For **any** initialization $x^0 \in \mathbb{R}^d$

$$f(x^k) - f(x^*) = \mathcal{O}\left(\frac{1}{k^2}\right)$$

Global convergence

$$x^{k+1} = x^k - \left(\nabla^2 f(x^k) + \sqrt{H \|\nabla f(x^k)\| \mathbf{I}} \right)^{-1} \nabla f(x^k)$$

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↑
**Convex and has
Lipschitz Hessian**

Global convergence

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Any optimum

Global convergence

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No line search or subproblems!

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$$x^{k+1} = x^k - \left(\nabla^2 f(x^k) + \sqrt{H \|\nabla f(x^k)\| \mathbf{I}} \right)^{-1} \nabla f(x^k)$$

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No line search or subproblems!

Matches rate of cubic Newton!

Proof idea: mimic cubic Newton

Define $r_k = \|x^{k+1} - x^k\|$

Proof idea: mimic cubic Newton

Define $r_k = \|x^{k+1} - x^k\|$

Cubic Newton:

$$x^{k+1} = x^k - (\nabla^2 f(x^k) + Hr_k \mathbf{I})^{-1} \nabla f(x^k)$$

Proof idea: mimic cubic Newton

Define $r_k = \|x^{k+1} - x^k\|$

Cubic Newton:

$$x^{k+1} = x^k - (\nabla^2 f(x^k) + Hr_k \mathbf{I})^{-1} \nabla f(x^k)$$

Our Newton:

$$x^{k+1} = x^k - (\nabla^2 f(x^k) + \lambda_k \mathbf{I})^{-1} \nabla f(x^k)$$

Proof idea: mimic cubic Newton

Define $r_k = \|x^{k+1} - x^k\|$ and $\lambda_k = \sqrt{H \|\nabla f(x^k)\|}$

Cubic Newton:

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Idea. Everything is fine if $H r_k \approx \lambda_k$

Proof idea: mimic cubic Newton

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$$x^{k+1} = x^k - (\nabla^2 f(x^k) + Hr_k \mathbf{I})^{-1} \nabla f(x^k)$$

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$$x^{k+1} = x^k - (\nabla^2 f(x^k) + \lambda_k \mathbf{I})^{-1} \nabla f(x^k)$$

Idea. Everything is fine if $Hr_k \approx \lambda_k$

Easy part: $Hr_k \leq \lambda_k$

Proof sketch

$$r_k = \|x^{k+1} - x^k\|$$

$$\lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

Proof sketch

$$r_k = \|x^{k+1} - x^k\| \qquad \lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

Lemma 1. $H r_k \leq \lambda_k$ **(Regularization is big enough)**

Proof sketch

$$r_k = \|x^{k+1} - x^k\| \quad \lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

Lemma 1. $Hr_k \leq \lambda_k$ **(Regularization is big enough)**

$$r_k = \|(\nabla^2 f(x^k) + \lambda_k \mathbf{I})^{-1} \nabla f(x^k)\| \leq \frac{1}{\lambda_k} \|\nabla f(x^k)\| = \frac{\lambda_k}{H}$$

Proof sketch

$$r_k = \|x^{k+1} - x^k\| \qquad \lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

Lemma 1. $H r_k \leq \lambda_k$

Lemma 2. $\|\nabla f(x^{k+1})\| \leq 2\|\nabla f(x^k)\|$

(No blow-up in gradients)

Proof sketch

$$r_k = \|x^{k+1} - x^k\| \quad \lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

Lemma 1. $H r_k \leq \lambda_k$

Lemma 2. $\|\nabla f(x^{k+1})\| \leq 2\|\nabla f(x^k)\|$

Lemma 3. $f(x^{k+1}) \leq f(x^k) - \frac{2}{3} \lambda_k r_k^2$ **(Descent)**

Follows from Lemma 1

Proof sketch

$$r_k = \|x^{k+1} - x^k\| \quad \lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

Lemma 1. $H r_k \leq \lambda_k$

Lemma 2. $\|\nabla f(x^{k+1})\| \leq 2\|\nabla f(x^k)\|$

Lemma 3. $f(x^{k+1}) \leq f(x^k) - \frac{2}{3} \lambda_k r_k^2$

Not sufficient to show a good rate.

It's time for a **new trick!**

Proof sketch

$$r_k = \|x^{k+1} - x^k\| \quad \lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

Lemma 1. $H r_k \leq \lambda_k$

Lemma 2. $\|\nabla f(x^{k+1})\| \leq 2\|\nabla f(x^k)\|$

Lemma 3. $f(x^{k+1}) \leq f(x^k) - \frac{2}{3}\lambda_k r_k^2$

$$\mathcal{I}_\infty = \left\{ k : \|\nabla f(x^{k+1})\| \geq \frac{1}{4}\|\nabla f(x^k)\| \right\}$$

Proof sketch

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Lemma 4. If $k \in \mathcal{I}_\infty$, $f(x^{k+1}) \leq f(x^k) - c(f(x^k) - f^*)^{\frac{3}{2}}$

if $k \notin \mathcal{I}_\infty$, $\|\nabla f(x^{k+1})\| \leq \frac{1}{4}\|\nabla f(x^k)\|$

Proof sketch

$$r_k = \|x^{k+1} - x^k\| \quad \lambda_k = \sqrt{H \|\nabla f(x^k)\|}$$

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Bonus: superlinear rate

$$x^{k+1} = x^k - (\nabla^2 f(x^k) + \lambda_k \mathbf{I})^{-1} \nabla f(x^k)$$

Theorem. If $\nabla^2 f(x) \succcurlyeq \mu \mathbf{I}$ and $\|\nabla f(x^0)\| \leq \frac{\mu^2}{4H}$

$$\|\nabla f(x^{k+1})\| \leq \frac{2\sqrt{H}}{\mu} \|\nabla f(x^k)\|^{\frac{3}{2}}$$

Bonus: superlinear rate

$$x^{k+1} = x^k - (\nabla^2 f(x^k) + \lambda_k \mathbf{I})^{-1} \nabla f(x^k)$$

Theorem. If $\nabla^2 f(x) \succcurlyeq \mu \mathbf{I}$ and $\|\nabla f(x^0)\| \leq \frac{\mu^2}{4H}$

$$\|\nabla f(x^{k+1})\| \leq \frac{2\sqrt{H}}{\mu} \|\nabla f(x^k)\|^{\frac{3}{2}}$$

Bonus: superlinear rate

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$\|\nabla f(x^k)\| \leq \varepsilon$ **after** $\mathcal{O}\left(\log \log \frac{1}{\varepsilon}\right)$ **iterations**

Summary

$$x^{k+1} = x^k - (\nabla^2 f(x^k) + \lambda_k \mathbf{I})^{-1} \nabla f(x^k)$$

$$f(x^k) - f(x^*) = \mathcal{O}\left(\frac{1}{k^2}\right)$$

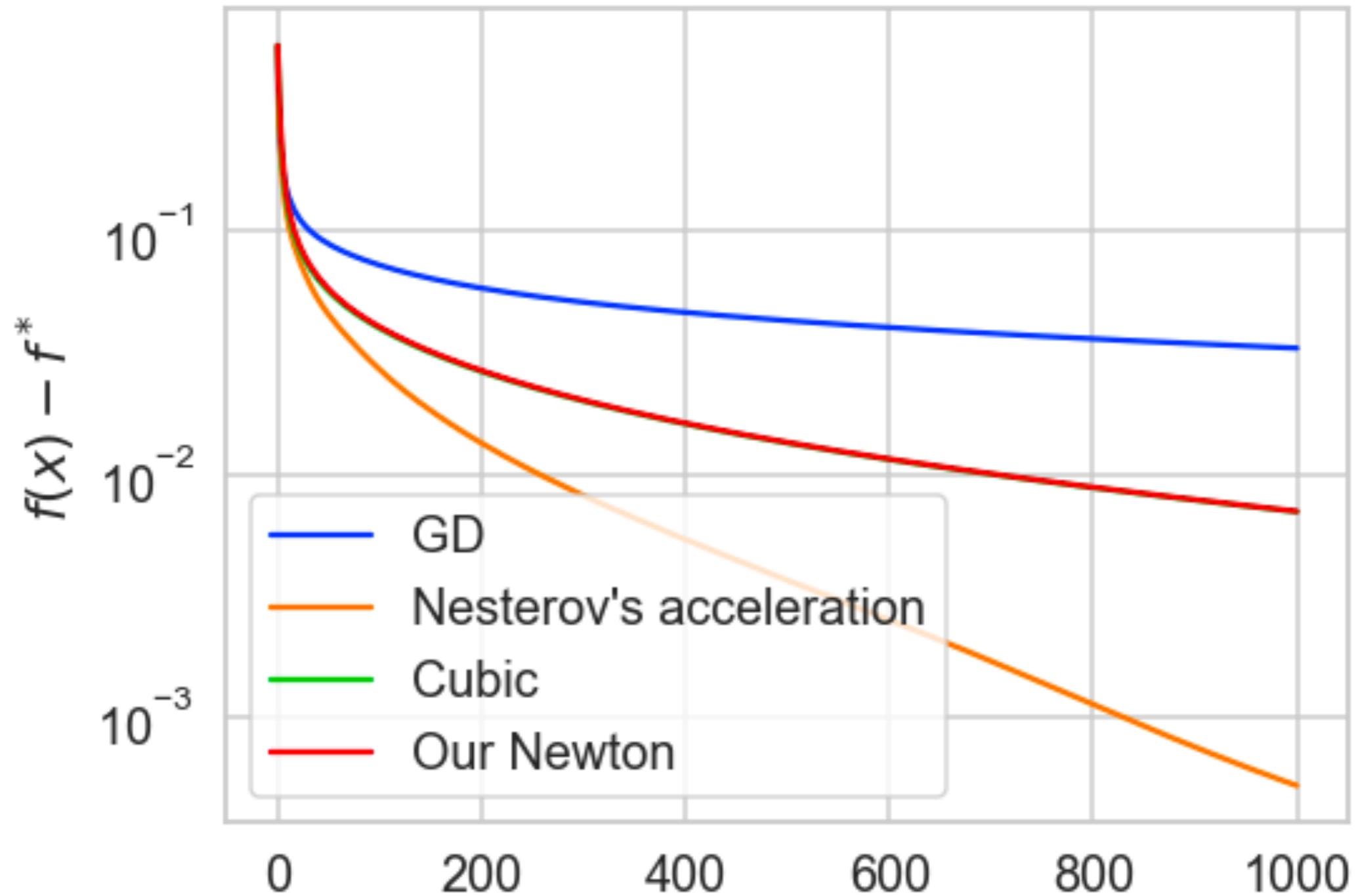
$$\mathcal{O}\left(\log \log \frac{1}{\varepsilon}\right) \quad \text{locally}$$

Intuition: it's almost like cubic Newton

Talk structure

- 1. Problem**
- 2. Historical remarks**
- 3. Key idea**
- 4. Theory overview**
- 5. Experiments**
- 6. Conclusion**

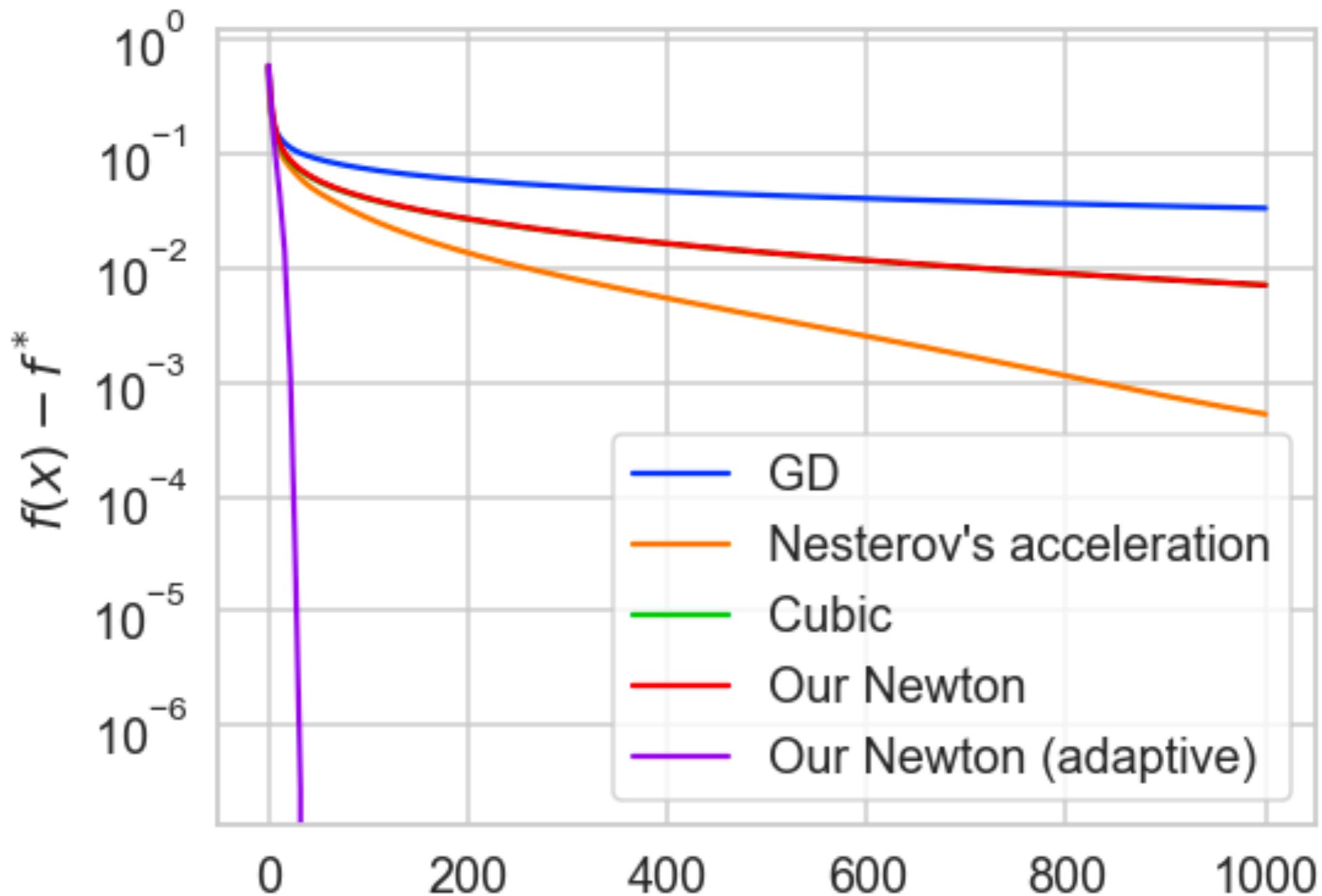
Experiments



What if we don't know H

- 1: **Input:** $x^0 \neq x^1 \in \mathbb{R}^d$
- 2: Initialize $H_0 = \frac{\|\nabla f(x^1) - \nabla f(x^0) - \nabla^2 f(x^0)(x^1 - x^0)\|}{\|x^1 - x^0\|^2}$
- 3: **for** $k = 1, 2, \dots$ **do**
- 4: $M_k = \frac{\|\nabla f(x^k) - \nabla f(x^{k-1}) - \nabla^2 f(x^{k-1})(x^k - x^{k-1})\|}{\|x^k - x^{k-1}\|^2}$
- 5: $H_k = \max \left\{ M_k, \frac{H_{k-1}}{2} \right\}$
- 6: $\lambda_k = \sqrt{H_k \|\nabla f(x^k)\|}$
- 7: Compute $x^{k+1} = x^k - (\nabla^2 f(x^k) + \lambda_k \mathbf{I})^{-1} \nabla f(x^k)$
- 8: **end for**

Experiments



Talk structure

- 1. Problem**
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What's next?

1. **Nonsmooth problems**
2. **Inexact/subspace updates**
3. **Acceleration**
4. **Minmax optimization**
5. **Stochastic Newton (**very hard!**)**
6. **Practical quasi-Newton variants**

90% is due to Nesterov & Polyak

Polyak



Nesterov



90% is due to Nesterov & Polyak

**“If I have seen further it is by standing on ye
sholders of Giants”, Newton, 1676**

Polyak



Nesterov

